

## Section 12.5: Lines and Planes

A line in 3-space is given by parameterized vector equation.

$$\mathbf{r}(t) = \mathbf{p} + t\mathbf{v}$$

where  $\mathbf{p}$  = position vector of a point on  $\ell$ , and  $\mathbf{v}$  = direction of line

Ex: Compute the vector equation of the line through  $(-6, 2, 3)$  and parallel to line  $\mathbf{r}(t) = \langle 0, 2, -1 \rangle + t\langle -2, 1, 5 \rangle$

Sol: Given  $\mathbf{p} = \langle -6, 2, 3 \rangle$  because of parallelism  $\mathbf{v} = \langle -2, 1, 5 \rangle$  is a valid direction vector for the desired line  
 $\therefore \mathbf{r}(t) = \langle -6, 2, 3 \rangle + t\langle -2, 1, 5 \rangle$

The parametric equations of a line are

$$\begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases} \quad \text{Component functions of the vector form}$$

Ex: For  $\ell$  and  $m$  as in the previous example, we simplify vector equation  $\mathbf{r}(t) = \langle -6-2t, 2+t, 3+5t \rangle$

$$\mathbf{m}(t) = \langle 2-2t, 2+t, -1+5t \rangle$$

$\hookrightarrow$

$\therefore$  has parametric equations

$$\begin{cases} x = -6-2t \\ y = 2+t \\ z = -1+5t \end{cases}$$

$\hookrightarrow$  ... has parametric equations

$$\begin{cases} x = -6-2t \\ y = 2+t \\ z = -1+5t \end{cases}$$

A line can also be represented (sometimes) by symmetric equation.

$$\frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c} \quad \text{Component functions of the vector form}$$

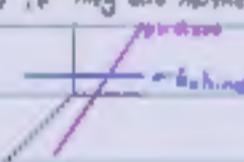
Ex: For  $\ell$  as above we had parametric equations

$$\begin{cases} x = -6-2t \\ y = 2+t \\ z = -1+5t \end{cases} \quad \hookrightarrow \begin{cases} \frac{y+6}{-2} = t \\ \frac{y-2}{1} = t \\ \frac{z-3}{5} = t \end{cases} \quad \hookrightarrow \frac{x+6}{-2} = \frac{y-2}{1} = \frac{z-3}{5}$$

are the symmetric equations of  $\ell$

Some Terminology: Two lines are

- ① parallel if their direction vectors are parallel
- ② intersecting if they have a common point
- ③ skew if they are neither parallel nor intersecting



Ex: Classify as parallel, intersecting, or skew:

$$\mathbf{l}_1(t) = \langle 5-12t, 3+9t, 1-3t \rangle$$

$$\mathbf{l}_2(t) = \langle 3+8t, -6t, 7+2t \rangle$$

$$\text{Sol: } \mathbf{l}_1(t) = \langle 5, 3, 1 \rangle + t\langle -12, 9, -3 \rangle \quad \mathbf{l}_2(t) = \langle 3, 0, 7 \rangle + t\langle 8, -6, 2 \rangle$$

$$\text{Unit vectors: } \frac{1}{\sqrt{144}} \mathbf{v}_1 = \frac{1}{\sqrt{144}} \langle -12, 9, -3 \rangle = \frac{1}{12} \langle -12, 9, -3 \rangle = \frac{1}{12} \langle 4, 3, -1 \rangle$$

$$\frac{1}{\sqrt{64}} \mathbf{v}_2 = \frac{1}{\sqrt{64}} \langle 8, -6, 2 \rangle = \frac{1}{8} \langle 8, -6, 2 \rangle = \frac{1}{8} \langle 4, -3, 1 \rangle \quad \text{multiple}$$

$$\frac{1}{12} \mathbf{v}_1 = -\frac{1}{8} \mathbf{v}_2, \text{ so } \mathbf{l}_1 \text{ is parallel to } \mathbf{l}_2$$

Sol (Intersect):

Check if  $\mathbf{l}_1$  and  $\mathbf{l}_2$  intersect:

Not looking for collision of line  $\mathbf{l}_1(t_0) = \mathbf{l}_2(t_0)$  rather that they cross the same point at any (even if different) times

Solve  $\mathbf{l}_1(t) = \mathbf{l}_2(s)$  i.e.  $\langle 5-12t, 3+9t, 1-3t \rangle = \langle 3+8s, -6s, 7+2s \rangle$

$$\begin{cases} 5-12t = 3+8s \\ 3+9t = -6s \\ 1-3t = 7+2s \end{cases} \quad \hookrightarrow \begin{cases} -12t+8s = -2 \\ 9t+6s = -3 \\ -3t-2s = 6 \end{cases} \quad \begin{cases} 6t-4s = 1 \\ 3t+2s = -1 \\ 3t+2s = -6 \end{cases}$$

can't both be true  
implies  $-1 = 3t+2s = 6 - 1 = 6$ !

So these lines do not intersect

Recall: A plane in 3-space has vector equation  $\vec{n} \cdot (\vec{x} - \vec{p}) = 0$

normal vector → vector → point on the plane

Ex Compute the plane through  $(1, 3, 4)$  and perpendicular to  $\langle -2, 1, 3 \rangle$

Sol:  $\vec{n} \cdot (\vec{x} - \vec{p}) = 0 \Rightarrow \langle -2, 1, 3 \rangle \cdot \langle x-1, y-3, z-4 \rangle = 0 \Rightarrow -2(x-1) + 1(y-3) + 3(z-4) = 0$

Any vector starting on line and ending at  $P$  are in plane.

Ex (2): Compute the plane through the point  $(3, 5, -1)$  and containing the line

Sol:  $\vec{p} = \langle 3, 5, -1 \rangle$  need  $Q$ , a point on  $\ell$  lets use  $Q = \langle 6 \rangle = \langle 4, -1, 0 \rangle$

$\vec{u} = \langle 3, 4, 5-1, -1-0 \rangle = \langle 1, 6, -1 \rangle$   $\vec{v}$  = direction vector of the line

$\vec{l}(t) = \langle 4, -1, 0 \rangle + t \langle 1, 6, -1 \rangle$   $\vec{u} \times \vec{v} = \vec{n} = \begin{vmatrix} i & j & k \\ 1 & 6 & -1 \\ 1 & 2 & -3 \end{vmatrix} = i \begin{vmatrix} 6 & -1 \\ 2 & -3 \end{vmatrix} - j \begin{vmatrix} 1 & -1 \\ 1 & -3 \end{vmatrix} + k \begin{vmatrix} 1 & 6 \\ 1 & 2 \end{vmatrix} = i(18-2) - j(3-1) + k(-2-6)$

$\vec{n} \cdot (\vec{x} - \vec{p}) = 0 \Rightarrow \langle -16, -2, 4 \rangle \cdot \langle x-3, y-5, z+1 \rangle = 0 \Rightarrow -16(x-3) - 2(y+5) + 4(z+1) = 0$

$\begin{cases} x = 4 - t \\ y = 2t - 1 \\ z = -3t \end{cases}$

both must lie in the plane

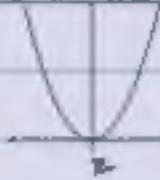
## Section 12.6: Quadratic Surfaces (textbook calls it Quadric surfaces)

IDEA: We want to study degree 2 polynomials and their solution sets in 3-space.  $\rightarrow$  hard in general

$\bullet$   $P(x, y, z) = x^2 - z$  a "degenerate" because it doesn't depend on all of the variables (would just be done in  $x, z$  plane)

Solution set:  $P(x, y, z) = 0$  if and only if  $x^2 = z$  if and only if  $x^2 = z$

Picture in  $xz$ -plane:

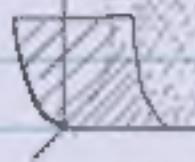


$y=0$

This solution set is actually a (parabolic) cylinder.

one slice at any  $x$  or  $z$  value

Picture in 3-space



kind of like a skateboard ramp" because parabola solution same for all values of  $y$   
folding a paper

It turns out, "up to" translation, reflection and rotation, there are only 6 nondegenerate quadratic surfaces

Name	Equation
Ellipsoid	$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$
Cone	$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 0$
Elliptic Paraboloid	<i>Solve for next time</i>